

BJ-2011 Position Controller
(Single Stepper -SH)

Manual

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This Product Pass ISO9001:2016 quality system authentication

Summarize:

WUXI BOKIN Co. specialty be engaged in computer's technology and industry automation technology and product's research, design, make and sale. Use company engineer's advanced technique and rich experience in printing, cut bag machine, medical, etc, We provide advanced automation control system for this machine manufacture.

BJ-2011 position control system, it's main specialty is absorb similar system's advantage, go by integration design, it's function is full, high performance, high reliability, easy to install and maintain, etc. Now this product is used by every manufactures, and received user's trust and good reputation.

ONE. Main technique index

- 1 Wide Power supply: 110--250V(AC); 50Hz/60Hz; 1A.
- 2 Suit range: single, duplicate membrane bottom seal, warm and cordial bottom seal, full-automatic (include stand, zipper bag etc.) and other fixed length position control equipment (medical pack etc.)
- 3 Roller diameter: 0.0~149.9mm
- 4 Fixed LENGTH: 0000~9999mm
- 5 SPEED: 0~300 part/min.
- 6 NUMBER count: 000~999
- 7 BATCH count: 0000~999
- 8 Outline-dimensions: 260mm(w)*130mm(h) *80mm(d).
- 9 weight: 1.6kg

CH.2 . Operate

System is realtime control,After parameter setting up,execute immediately, don't need press "RESET" key.

1 Open power supply, system is power on state.
2 press "SETUP"key, up-down loop move setting parameter,items is:

2.1 L Length setting, 4 digit display,mm.

2.2 n Integer preset, 4 digit display, PCS. (default:100),Alarm before 5 pcs.

2.3 S High speed limit for Stepper motor, 2 digit display,0~99. (0=100%,1—99%)。

2.4 H Color photoelectricity detection's valid range,when make printing products use. If track to L+H value, color code not found,system acquiesce in this end product,and alarm,continuous 3 times for this case, stop machine.

If H=0: search Color all times.

2.5 F password, 4 digit show. Below project is submenu,exact input password (21), these parameter will show, otherwise no show.

2.5.1 d pull roller diameter, 3 digit show, 00.0~149.9mm。

2.5.2 \square whole Integer pull time preset, 0~9: 1--10s。

2.5.3 b: machine type,0--99

2.5.3.1 when b=0, count to "n" value,alarm and pull relay (JD2) will output.

2.5.3.2.1 when b=1, count to "n", machine will stop.

2.5.3.3 when b =2--99, count to n, machine will pause for 0.2—9.9s, meanwhile pull relay switch on(JD2), meanwhile main relay auto start work.

2.5.4 E: stepper motor curve.0~8 。 Setting different value,motorspeed is different, slow speed high tor. E value slow to fast is: 8,7,6,5,4,3,2,1,0。

2.5.5 C CONK Time befor roll [0--99]*0.1S

2.5.6 U delay time before cuttingknife work[0--99]*0.1s

2.5.7 1. Delay time after CONK(JD6) [0--99]*0.1s

2.5.8 2. WORK MODE:

0: ROLL FIRST, 1: CUTTING FIRST(JD3)。

2.5.9 3. WHEN RUNNING, After receiving the single of HALL Switch, controller will output JD4 [0--99]*0.1S.

