

| Performance                             |  |  | SVC control mode   | V/F control mode   |  |  |  |  |
|---|--|--|--|--|--|--|--|--|
|   | Speed control mode   |  | Hybrid vector control mode<br>Speed Sensorless High Speed and Torque Control   | V/F control mode   |  |  |  |  |
|   | Max rotate speed   |  | Relate to 245Hz  | 400Hz  |  |  |  |  |
|   | Carrier frequency  |  | 1.0 ~ 10.0kHz (Power derating when the carrier frequency is higher than the default value)   |  |  |  |  |  |
|   | Over load capacity   |  | 150% rated current for 1 minutes   |  |  |  |  |  |
|   | Speed control range  |  | 1:100 (General motor)  | Approximately 1:50   |  |  |  |  |
| Cor                                     | Speed<br>Frequency   | Digital input<br>(-10°C ~ 40°C)  | ±0.5%  | $\pm 0.01\%$ (Frequency accuracy)                              |  |  |  |  |
| Control performance                     | Accuracy   | Analog input<br>(25°C±10°C)  | ±0.5%  | $\pm 0.2\%$ (Frequency accuracy)                               |  |  |  |  |
| perf                                    | Speed control mode   |  | Robust control   | 1  |  |  |  |  |
| for                                     | Speed control response   |  | 200rad/s (-3dB)  | /  |  |  |  |  |
| ma                                      | Torque control accuracy  |  | <±8% (General motor)   | /  |  |  |  |  |
| anc                                     | Torque   | e control response   | 2krad/s (-3dB)   | /  |  |  |  |  |
| ĕ                                       | Cons   | tant power range   | 1:4  | 1  |  |  |  |  |
|   | Spe  | eedless control  | 1  | 1  |  |  |  |  |
|   | Sta  | art-up torque  | More than 150%   |  |  |  |  |  |
|   | 1  | Forque limit   | Can be set within four quadrants of forward<br>motoring, forward generating, reverse motoring<br>and reverse generating. Setting range: 0~150%<br>(up to 200% due to different motors in the drive<br>combination)   | Available for motoring and generating states with 0~150% range |  |  |  |  |
| Main<br>control<br>protecti<br>performa | & operat<br>self-le<br>Mecha<br>mode,<br>function<br>freque<br>speed | ion, prohibit reverse mod<br>arning, Torque boost, Suj<br>nical loss compensation s<br>Built-in PID function, Mo<br>on, fault retry, timing cont<br>ncy hold function, Mome<br>reached detection output, | torque control switching operation, the default speed tracking fast start function, high efficiency<br>le selection, to prevent regenerative stall function, DC braking, energy braking, static and rotation<br>ppress unstable function, Removable terminal block with parameter backup function, Droop control,<br>setting, Speed deviation limit during acceleration / deceleration, Multi-speed program operation, Stop<br>otor running, skip function, contact acceleration and deceleration function, cooling fan ON / OFF<br>trol, S curve acceleration and deceleration, acceleration / deceleration time switching, speed /<br>nt detection output, 2-wire and 3-wire control, forward and reverse switching, pre-excitation, torque /<br>, FCL over-current fault avoidance, MODBUS communication. |  |  |  |  |  |
|   | option<br>speed  | al fault protection, extern  | GBT module abnormalities, overcurrent protection, over voltage protection, under voltage protection,<br>nal fault protection, Over speed and over torque protection, communication error, speed control error,<br>contactor open protection.   |  |  |  |  |  |
| Operati<br>keypa                        |  | ter via the operation keypad<br>ck   |  |  |  |  |  |  |
|   | Application site   |  | Vertical installation indoor, avoid direct sunlight; no visible dust, corrosive gases, flammable gas, oil mist, water vapor, drip or salt and so on  |  |  |  |  |  |
| -                                       | Altitude   |  | Under 1000 meter. ( Derate when higher than 1000 meters , output current reduce about $10\%$ of rated current per 1000 meter height )  |  |  |  |  |  |
| Bnvi                                    | Enviro   | oment temperature  | -10 °C ~ $+40$ °C. environment temperature between $40$ °C ~ $50$ °C need to lower output power  |  |  |  |  |  |
| Enviromental                            | Envi   | roment humidity  | Smaller than 95%RH, no drop condenses  |  |  |  |  |  |
|   | Vibration  |  | Smaller than 5.9m/s <sup>2</sup> (0.6g)  |  |  |  |  |  |
|   | Storage temperature  |  | -40°C ~ +70°C  |  |  |  |  |  |
|   | Protection grade   |  | IP20   |  |  |  |  |  |
| Structure                               | Co   | ooling method  | Forced air cooling   |  |  |  |  |  |
| Installation method                     |  |  | Wall hanging and cabinet installation  |  |  |  |  |  |



# EN700 intelligent high performance frequency inverter



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# **About us**



Shenzhen Encom Electric Technologies CO., LTD is a state-level high-tech enterprise with independent intellectual property rights, focusing on industrial automation products' development, production and sales. The main products include frequency inverter/ac drive, servo controller, PLC, new energy systems.

ENC company was established in 2004, has passed ISO9001: 2008 quality management system certification and the European Union CE certification, won the National Innovation Fund, the Shenzhen strategic emerging industries fund, product innovation award, the most investment value award and repeatedly won "China top ten low-voltage inverter domestic brands" title.



- 1. Won National Innovation Fund enterprise, China's high-tech enterprise
- 2. Repeatedly won "China top ten domestic brands" title
- 3. With more than 13 years of rich experience R&D team
- 4. With completely independent intellectual property rights, has dozens of

#### patents

- 5. Master the world's leading asynchronous, synchronous vector control
- technology and torque control technology
- 6. ISO9001:2008 system certification unit, strict and standard information quality control system
- 7. Has more than 30 offices in China
- 8. ENC provide quality products and services for more than 30 countries' industrial user





## EN700 intelligent high performance frequency inverter

EN700 series frequency inverter is a new generation of motor driver. It is innovative on the basis of classical flux vector control. It can accurately measure and calculate various parameters of motor, monitor and compensate mechanical loss and motor temperature, etc. High speed and powerful computing capabilities enable efficient and complex drive control to meet the drive requirements of a wide range of high-end equipments.







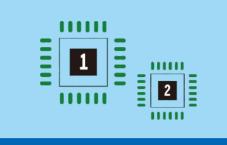


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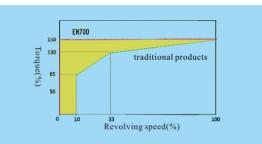


opportunities for innovation, fully reserved for a variety of industrial application parameters of the secondary development.



Dual-core operation: faster than ever before

Dual CPU system operates faster and more responsive. Within 200mS to complete a smooth start for free high-speed rotating motor.



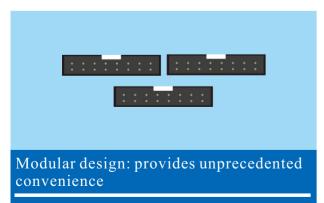
#### Rich in function configuration: meeting various application requirements

Motor temperature detection, mechanical loss compensation, suppression of unstable function; power 4.0~55KW section is equipped with built-in braking unit, 30KW and above standard with builtin DC reactor.



Intelligent learning: no need to set more parameters

Intelligent induction user-set habits, self-identification user-set parameters, with the menu of check mode, can monitor multiple sets of parameters.



Terminal can be removed and backup data, so no need to disassemble the control cables and reset parameters.



A variety of protocols: the ultimate refreshing protocol experience

Powerful access to networking capabilities, support for Canopen, Modbus, Ethercat, Profibus-DP, and other protocols. Monitor and operate from your PC.



**Product features** 

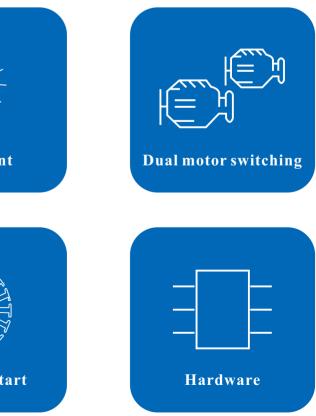


**Parallel expansion** 

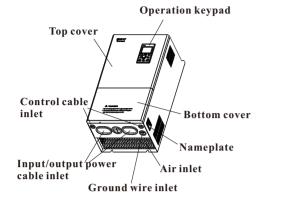
**Speeding start** 

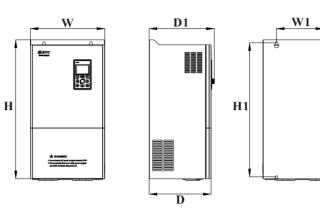
## Intelligent drive Precision motion

- First-class control algorithm
- Abundant application features
- Abundant scalability and more user-friendly operation
- Complete hardware configuration and high reliability
- Aesthetic body and scientific structure design



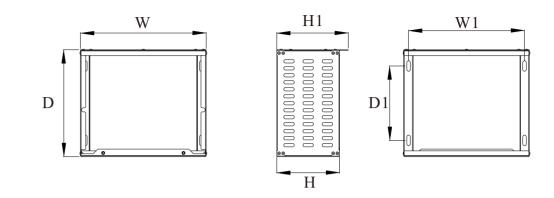






| Inverter model | W ( mm) | W1(mm) |      | H1(mm) | D(mm) | D1(mm) | Fix Hole<br>(mm) | Packing<br>size<br>(cm) | Gross<br>weight<br>(kg) |
|----------------|---------|--------|------|--------|-------|--------|------------------|-------------------------|-------------------------|
| EN700-4T0040   |         | 100    | 320  | 306    | 192   | 205    | 6                | 38.5*23.5*27            | 8                       |
| EN700-4T0055   | 160     |        |      |        |       |        |                  |                         |                         |
| EN700-4T0075   |         |        |      |        |       |        |                  |                         |                         |
| EN700-4T0110   | 210     | 150    | 365  | 349    | 200   | 213    | 7                | 42.5*28.5*28            | 11                      |
| EN700-4T0150   | 210     |        |      |        |       |        |                  |                         |                         |
| EN700-4T0185   | 250     | 190    | 420  | 400    | 210   | 223    | 9                | 48*31.5*28.5            | 16                      |
| EN700-4T0220   |         |        |      |        |       |        |                  |                         | 10                      |
| EN700-4T0300   | 200     | 220    | 560  | 540    | 260   | 263    | 9                | 62*37.5*43.5            | 27                      |
| EN700-4T0370   | 300     |        |      |        |       |        |                  |                         | 37                      |
| EN700-4T0450   | 326     | 260    | 610  | 590    | 265   | 278    | 9                | 68.5*42*46              | 48                      |
| EN700-4T0550   | 520     |        |      |        |       |        |                  |                         | 40                      |
| EN700-4T0750   | 360     | 250    | 605  | 575    | 325   | 348    | 13               | 69*46*53.5              | (9)                     |
| EN700-4T0900   |         |        |      |        |       |        |                  |                         | 68                      |
| EN700-4T1100   | 430     | 250    | 710  | 680    | 340   | 353    | 13               | 79*53*55                | 88                      |
| EN700-4T1320   |         |        |      |        |       |        |                  |                         | 89                      |
| EN700-4T1600   | 510     | 370    | 1069 | 1035   | 430   | 443    | 13               | 114*61*64               | 148                     |
| EN700-4T2000   | 560     | 420    | 1069 | 1035   | 430   | 443    | 13               | 114*66*64               | 170                     |
| EN700-4T2200   |         |        |      |        |       |        |                  |                         | 168                     |

## **Optional base and base dimensions**



| Inverter model | Standard base | W(mm) | D(mm) | H(mm) | W1(mm) | D1(mm) | Mounting<br>holes<br>(mm) |
|----------------|---------------|-------|-------|-------|--------|--------|---------------------------|
| EN700-4T0750   | SP-BS7-0900   | 360   | 306   | 180   | 332    | 213    | 30*10                     |
| EN700-4T0900   |               |       |       |       |        |        |                           |
| EN700-4T1100   | SP-BS7-1320   | 430   | 320   | 180   | 402    | 228    | 30*10                     |
| EN700-4T1320   |               |       |       |       |        |        |                           |
| EN700-4T1600   | SP-BS7-1600   | 510   | 404   | 205   | 446    | 340    | Φ10                       |
| EN700-4T2000   | SP-BS7-2200   | 560   | 404   | 204   | 496    | 340    | Φ10                       |
| EN700-4T2200   |               |       |       |       |        |        |                           |

The keyboard size (unit: mm)

